



# Manohar Kuse

Computer Vision / ML Engineer  
Zürich, Switzerland

## About Me

Senior Computer Vision Engineer with a PhD in Robotics and 5+ years of industry experience building real-time SLAM, 3D reconstruction, and ML systems for robotics and AR. Skilled at delivering scalable cloud deployments and maintaining production-grade pipelines.

I thrive in collaborative teams, enjoy technical discussions, and value knowledge sharing. I'm easy-going, curious, and driven by a desire to build meaningful, real-world systems.

Currently seeking a senior technical role that offers opportunities to learn, grow, and contribute to impactful products at the intersection of ML, vision, and scalable deployment.

## Contact

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- [LinkedIn Profile](#)

## Personal

Indian citizen  
Open B-Permit in Switzerland

### Languages:

- English (Fluent)
- German (A2)
- Marathi, Hindi

### Hobbies:

Skiing, Hiking, Sailing, Reading

## Working Experience

### Senior Computer Vision Engineer

Jan 2022 - Dec 2024

Magicleap, Zürich, Switzerland

- Visual-Inertial SLAM - KPI reporting, performance analysis
- Relocalization System for headpose
- 3D Kinematics for sensor fusion on non-inertial base
- Production code base maintenance

### Robotics Engineer

Apr 2020 - Nov 2021

Rovenso AG, Fribourg, Switzerland

- Docking, Path planning and controller for ground robot
- Configuration management system for deployment
- Robotics UI designing
- Sensor fusion (Lidar+IMU, Lidar+Wheel encoders, GPS+IMU)

## Skills

### Programming Languages

- C++, Python — Proficient in efficient, production-ready code; experience with performance-critical and high-level scripting.

### Machine Learning & 3D Computer Vision

- Frameworks:** Tensorflow, keras, pytorch
- Libraries:** OpenCV, OpenGV, PCL(Point Cloud Library)
- Specializations:** Feature extraction, relocalization, pose estimation, 3D reconstruction, SLAM, NeRF, Gaussian Splatting

### Robotics

- Tools:** ROS, RViz, Ceres Solver, re:run, GTSAM
- Experience:** Real-time SLAM pipelines, sensor fusion, trajectory planning and optimization

### Backend & DevOps

- Flask (RESTful API development), Docker, Git, MongoDB, SQL
- DevOps: CI/CD with GitHub Actions, Dockerized microservices
- Google Cloud Platform (GCP) — Compute Engine, Cloud Storage, BigQuery, Cloud SQL

### Softskills

- Curious and fast learner, Analytical and systems-minded.
- Adaptable, collaborative teamwork.

## Education

### Doctoral Studies (Ph.D)

Aug 2013 - Dec 2019

The Hong Kong University of Science and Technology (HKUST)

- Thesis: "Techniques for a failsafe Visual Inertial SLAM System"
- Learning to relocalize using streetview data
- Drone Kinematics and Control
- Web Frontends for KPI monitoring

### Bachelor of Technology (B.Tech)

2019 - 2020

The LNM Institute of Information Technology, Jaipur, India

- Communication and Computer Engineering

## Select Github Projects

\*Both projects related to my doctoral thesis (~2019)

### Kidnap recovery in VI-SLAM

- Relocalization in visual-inertial SLAM system
- Learned image descriptors
- 3D pose and alignment

<https://github.com/mpkuse/cerebro>

### Image Descriptor Learning

- Image level descriptors
- trained using street view
- Deep neural network architecture

[https://github.com/mpkuse/cartwheel\\_train](https://github.com/mpkuse/cartwheel_train)